

CONTINUATION METHOD AND TOPOLOGICAL INVARIATION

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ABSTRACT. The inversability of an linear bounded operator can be deduced from the inversability of an known linear operator with help of continuation method, with important generation in the degree theory. In this report are presented continuation method, equations with sum A-proper, where topological degrees generalized can be used and the study of similar equations, of tip $Lx = S(x) + p$, in which L is Fredholm unbounded operator with zero index and $N(L) \neq \{0\}$, having the majority properties of coincidents degrees.

In the last part are given two examples: one in the case of approximation method for A-proper and another example with Hammerstein abstract equation.

1. Preliminaries

Continuation method:

• Let X be a Banach space, Y a normate space and $L_0, L_1 \in L(X, Y)$ an bounded operators. We define the homotopi

$$L_t := (1-t)L_0 + tL_1$$

and we suppose that there exist a constant $C > 0$, such that $\|x\|_X \leq C \|L_t x\|_Y, \forall x \in X, t \in [0, 1]$.

The equation with sum A-proper

Let be the equation of form

$$(1) \quad Lx = S(x) + p.$$

where $L : X \mapsto Y$ is a linear operator A-proper, so $S : \bar{D} \subseteq X \mapsto Y$ an nonlinear operator with the property that the sum $T := L - S$ to be weak A-proper; X and Y separable Banach spaces and $\Gamma_n := (\{x_n\}, \{y_n\}, \{P_n\}, \{Q_n\})$ the schem (of approximation) projective complet given.

Lemma: *If L is injective continuous operator, then the equation (1) has at last one solution for each $p \in Y$.*

We suppose that L is an Fredholm operator with $N(L) \neq \{0\}$ and index zero. In this case $\dim N(L) = \text{codim } R(L)$ and there exist closed subspaces $X_1 \subset X$ and $Y_1 \subset Y$ with $\dim Y_1 = \dim N(L)$, such that $X = N(L) \oplus X_1, Y = Y_1 \oplus R(L)$, L is an injection on X_1 , and $L(X_1) = R(L)$. Let M an izomorfism of $N(L)$ on Y_1 , P the projection of X on $N(L)$ and $C := MP$. Because C is a compact operator and L is a A-proper operator, it fallows like the operator $L_\lambda := L + \lambda C$ is, also A-proper. Mach more, L_λ is Fredholm closed operator with index zero.

Theorem. *We suppose that the image $T(\bar{B})$ is closed, any ball $B \subset X$ and one of next sets,*

$$S^+ := \{x_n \in X; L_{\lambda_n} x_n = S(x_n) + p, \lambda_n \rightarrow 0_+\}$$

$$S^- := \{x_n \in X; L_{\lambda_n} x_n = S(x_n) + p, \lambda_n \rightarrow 0_-\}$$

is bounded by a constant wich doesn't depends of $n \geq N$, then the equation (1) has at last one solution for $p \in Y$.

Corollary. Let X a reflexive space, $K : X \rightarrow Y^*$ an bounded operator, weak continuous, with $R(K)$ dense in Y^* such that $Q_n^* K x = K x$, $L : X \rightarrow Y$ an Fredholm operator of index zero, $S : X \rightarrow Y$ is asymptotic zero operator, wich satisfy one of the next conditiones:

- (i) S is compact ;
- (ii) S is weak continuous ;
- (iii) S is semibounded.

If one of sets S^+, S^- is bounded, then equation (1) has at last one solution for $p \in Y$.

We suppose now that $D_L := D \cap D(L) \neq \emptyset$ and the nonlinear operator $T := L - S : \bar{D}_L \mapsto Y$ is A-proper in raport with schem Γ_L made before. If $p \notin T(\partial D_L)$, then generalized degree $D_L(T, D, p) := D(T, D_L, p)$ is well defined and has the property from the precedent section.

Proposition (Continuons Theorems)

Let $S : [0, 1] \times \bar{D} \mapsto Y$ such that the application $L-S : [0, 1] \times \bar{D}_L \mapsto Y$ to be a homotoic A-proper with respect to schem Γ_L , with $S(l, \cdot) = S$. If $Lx \neq S(t, x) - t p, \forall t \in [0, 1), x \in \partial D_L$ and $D_L(L - S(0, \cdot), D, p) \neq \{0\}$, then the equation (1) has at last one solution in \bar{D}_L .

2. Examples

1. The continuation method for schem A-proper.

Let Ω a bounded domain in R^m . We consider Dirichelt problem for a elliptic equation of divergential type

$$(1) \begin{cases} - \sum_{|\alpha| \leq 1} D^\alpha A_\alpha(x, u, u') + C(x, u, u') = f(x), & x \in \Omega \\ u(x) = 0 & x \in \partial\Omega \end{cases}$$

and we look to establish the existens of the generalized solution.

We note $\xi := \{\xi_\alpha \in R; |\alpha| \leq 1\} \in R^{1+m}$,
 $\xi(u) := \{D^\alpha u; |\alpha| \leq 1\}$

And we suppose that are fulfillment the next conditions:

(A₁) The functions $A_\alpha(x, \xi)$ satisfies Caratheodory conditions – they are measurable in $x \in \bar{\Omega}$ for each $\xi \in R^{1+m}$ and continue in ξ a.p.t. $x \in \bar{\Omega}$ - and we admit grow up of type $|A_\alpha(x, \xi)| \leq k_0 |\xi|^{p-1} + h_0(x), \forall x \in \bar{\Omega}, \xi \in R^{1+m}, |\alpha| \leq 1$, where $k_0 > 0, 1 < p < \infty$, then $h_0 \in L^q(\Omega)$, with $\frac{1}{p} + \frac{1}{q} = 1$;

(A₂) There exist the constants $c_0 \geq 0$ and $c_1 > 0$ such that

$$\sum_{|\alpha| \leq 1} [A_\alpha(x, \xi) - A_\alpha(x, \xi')] (\xi - \xi') \geq c_1 \left(\sum_{|\alpha| \leq 1} |\xi_\alpha - \xi'_\alpha|^p \right) - c_0 |\xi_0 - \xi'_0|^p$$

any $x \in \bar{\Omega}$ and $\xi \neq \xi'$;

(A₃) For each $x \in \bar{\Omega}$, the function $A_\alpha(x, \cdot) : R^m \mapsto R$ are odd, $A_\alpha(x, -\xi) = -A_\alpha(x, \xi)$, and positive omogeneous order $s > 0, A_\alpha(x, t\xi) = t^s A_\alpha(x, \xi), \forall t > 0$;

(C₁) The function $C(x, \xi)$ satisfaid Caratheodory condition and admits grow up $|C(x, \xi)| \leq k_1 |\xi|^{p-1} + h_1, \forall x \in \bar{\Omega}, \xi \in R^{1+m}$, where $k_1 > 0$ and $h_1 \in L^q(\Omega)$;

(C₂) There exist a continous function $k : R_+ \mapsto R_+$ with the property that $k(t) t^{-s} \rightarrow 0$ when $t \rightarrow \infty$ sach that, $|C(x, \xi(u))| \leq k(\|u\|_{1,p})$ for $u \in H^{1,p}(\Omega)$.

We will show that this hippotheses are sufficient for the existens of generalized solution of problem (1).

The hippotheses (A₁) and (C₁) we assure the Dirichlet forms:

$$a(u, v) := \sum_{|\alpha| \leq 1} \int_\Omega A_\alpha(x, \xi(u)) D^\alpha v dx$$

$$b(u, v) := \int_\Omega C(x, \xi(u)) v dx$$

are well defined for $\forall u, v \in H^{1,p}(\Omega)$ (where $H^{1,p}(\Omega)$ is a reflexive Banach space and separable); there are continuous functioning of $v \in H^{1,p}(\Omega)$, for $u \in H^{1,p}(\Omega)$ arbitrary fixed which is result from inequality of Hölder. It results that we can attach the problem (1) of functional equation

$$(2) \quad a(u, v) + b(u, v) = (f, v), \forall v \in H^{1,p}(\Omega)$$

with $f \in L^q(\Omega)$ given, with the solution we call (weak) generalized solution of problem (1).

Because $A(u) := a(u, \cdot)$ and $C(u) := b(u, \cdot)$ are functionable on $X := H_0^{1,p}(\Omega)$ we can define bounded and continuous operator, $A : X \mapsto X^*$ and $C : X \mapsto X^*$, by

$$\begin{aligned} (Au, v) &:= a(u, v), \forall v \in X \\ (Cu, v) &:= b(u, v), \forall v \in X, \end{aligned}$$

where (Au, v) and (Cu, v) represent $A(u)$ and $C(u)$ from X^* which is calculated in $v \in X$.

Form $f \in L^q(\Omega)$ there exist an $\omega_f \in X^*$ unique determinate for equation $(\omega_f, v) = (f, v)$, $\forall v \in X$.

The equation (2) is equivalent with operatorial equation

$$(3) \quad T(u) := Au + Cu = \omega_f,$$

determined by an $\omega_f \in X^*$ known and the operator $T := A + C : X \mapsto X^*$.

For the existence of solution (3) we applied the theory of applications A-proper; must build a projective scheme complete for application from X in X^* .

Let $E := \{e_1, \dots, e_n, \dots\}$ a system of linear independent elements, complete in X . We defined subspaces finite dimensional

$$X_n := Sp\{e_1, \dots, e_n, \dots\}$$

such that $\bigcup\{X_n; n \in N\}$ let be a dense set in X . For each $n \in N$ we associated the equation (2) an algebraic system, of n nonlinear equations,

$$(4) \quad a(u_n, e_j) + b(u_n, e_j) = (f, e_j), \quad 1 \leq j \leq n,$$

with determinate approximate solution, $u_n := a_1^{(n)}e_1 + \dots + a_n^{(n)}e_n$. We denote with $P_n : X \mapsto X_n$ the linear projection induced by system E and with $I_n : X_n \mapsto X$ linear injection of X_n in X . Because $Y := X^*$, we take $Y_n := X_n^*$ and we define the projection $Q_n : Y \mapsto Y_n$ like adjoint application of injective I_n , then $Q_n := I_n^*$.

$\Gamma_n := (\{X_n\}, \{Y_n\}, \{P_n\}, \{Q_n\})$ makes a complete projective of approximation scheme; but equation (4) is equation equivalent

$$(5) \quad T_n(u_n) := A_n u_n + C_n u_n = Q_n \omega_f$$

where $A_n := Q_n A / x_n$, $C_n := Q_n C / x_n$ and $T_n := A_n + C_n : X_n \mapsto Y_n$.

Lemma: In hypotheses $(A_1 - A_2)$ and (C_1) , the operators A and $T := A + C$ are A-proper with respect to the scheme Γ_n (then $T := A + C$ is an (weak) operator A-proper like the sum from an operator A weak A-proper and a compact operator C.

Theorem: In hypotheses (A) and (C) there exist at last a generalist solution of a problem (1), which can be obtained by approximating with the scheme Γ_n .

Proof: In the base of Lemma, the operators A and $T := A + C$ are A-proper with respect to scheme Γ_n .

A is odd and omogen positive of order $s_i > 0$, in the base of hypotheses (A_3) , but C has the properties

$$(6) \quad \frac{\|Cx\|}{\|x\|^s} \rightarrow 0 \text{ when } \|x\| \rightarrow \infty,$$

in the base of hypotheses (C_3) .

The set $B_n := P_n(B(O, r))$ is bounded and open in X_n for each $n \in N$, but \bar{B}_n and ∂B_n are closed in $P_n(\bar{B}(O, r))$.

For each $n \in N$ we consider the homotopic continuous

$$H_n(x, t) := A_n x + (1 - t)(C_n x - Q_n \omega_f), \quad \forall x \in \bar{B}_n, t \in [0, 1]$$

and we assert that there exist an $r > 0$ and a rank $N \geq 1$ such that $O \notin H_n(\partial B_n, [0, 1])$, $\forall n \geq N$.

If it wasn't like that we can find the row $\{x_m; x_m \in X_m\}$ and $\{t_m\} \subset [0, 1]$, such that $\|x_m\| \rightarrow \infty$ and

$$(7) \quad Q_m A x_m + (1 - t) Q_m (C x_m - \omega_f) = O, \quad \forall m \in N.$$

Because Q_m are linear uniformly bounded application, A is omogen positive of order $s > 0$ and $\|x_m\| \rightarrow \infty$, from (6) and (7) follows that

$$Q_m A z_m = \frac{(t_m - 1) Q_m (C x_m - \omega_f)}{\|x_m\|^s} \rightarrow 0, \text{ where}$$

$$z_m := \|x_m\|^{-1} x_m$$

Because $\|z_m\| = 1$ and $A_m z_m := Q_m A z_m \rightarrow 0$, we used the fact that A is an operator A -proper, it result that there exist an subrow $\{z_i\} \subset \{z_m\}$ and $z \in X$, with $\|z_m\| = 1$, such that $z_i \rightarrow z$ and $Az = 0$, are in contradiction with the propretes of A .

So, we can use the invariation to the homotopic of Brouwer degees and, because A_n is odd for each $n \in N$, using the Borsuk theorem, we obtain

$$d(T_n, B_n, Q_n \omega_f) = : d(H_n(\cdot, 0), B_n, O) =$$

$$= d(H_n(\cdot, 1), B_n, O) := d(A_n, B_n, O) \neq 0.$$

Because T is a weak operator, the generalized topological degree is well defined and it results from up $D(T, B, \omega_f) \neq \{0\}$; we deduce that there exist at last one solution $x \in B(O, r)$ of equation (3), which can be obtaine like weak limit (is hard T if is injectiv), of a subrow from the row of approximate equations solutions (5).

2. The abstract Hammerstein equation.

Let $A : X^* \mapsto X$ an compact and negative linear operator, but $N : X \mapsto X^*$ is an bounded and semicontinu operator, where X and X^* is a Banach space and his dual. If is satisfaid the corectivity condition $(Nu, u - \omega) \geq 0$ for all $u \in \partial D$, with D is an open and bounded set in X , and a certain $\omega \in D$, then Hammerstein equation $(I + AN) u = \omega$ has at last one solution in \bar{D} .

Proof: we consider the perturbation

$$N_\varepsilon u := N u + \varepsilon J(u - \omega)$$

where $J : X \mapsto X^*$ is the duality application

$$Jx := \left\{ f \in X^*; (f, x) = \|x\|^2 = \|f\|^2 \right\}$$

(for example Pascali – Sburlan [1, p. 109]); then N_ε has the same properties like N then the operator $P_\varepsilon := A N_\varepsilon : X \mapsto X$ is compact.

We show, first, with the continuation method that the equation $(I + P_\varepsilon)U = \omega$ admit a solution $u_\varepsilon \in D$. For this we most shown that the equation $(I + t P_\varepsilon)U = \omega$ has not solutions on ∂D for any $t \in [0, 1]$.

We suppose, by absurd, for $t \in [0, 1]$ there exist a solution $u_\varepsilon \in \partial D$ of this equation; then

$$0 = (N_\varepsilon u, u + t P_\varepsilon u - \omega) = (N_\varepsilon u, u - \omega) + t (N_\varepsilon u, A N_\varepsilon u)$$

Because A is nonnegative, $(N_\tau u, A N_\tau u) \geq 0$ it result

$$0 \geq (N_\varepsilon u, u - \omega) = (Nu, u - \omega) + \varepsilon (J(u - \omega), u - \omega) \geq \|u - \omega\|^2.$$

So $\omega = u \in \partial D$, in contradiction with what we had supposed.

In consequence, for each $\varepsilon > 0$, there exist a solution $u_\varepsilon \in D$ of equation $(I + P_\varepsilon)U = \omega$.
More then

$$(I + AN) u_\varepsilon = \omega - \varepsilon AJ(u_\varepsilon^- \omega) =: \omega_\varepsilon.$$

From this equality it results that $\omega_\varepsilon \rightarrow \omega$ in X , when $\varepsilon \rightarrow 0$, so ω is in the set $(I + AN)(D)$.
Because the product AN is an compact operator, we have $\omega \in (I + AN)(\bar{D})$, so what we have to proof.

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